CSC207: Javadoc and UML

To earn the credit for this lab, you must be present in the lab class. For this lab, and for the rest of the labs in this class, please make sure to submit by end of the lab class.

1 Overview

This week, you will implement two classes based on the UML diagrams. You'll also document the classes by providing doc comments for the Javadoc. Also, ask your TAs questions about assignment 1!

2 Log in and get things set up.

Use MarkUs to form a group with your lab partner. The MarkUs item for this lab is Lab5. This will require s1 to log in to MarkUs and invite s2 to form a group. Then s2 will need to log in and accept the invitation from s1. Take a note of the group MarkUs created for you. It will be of the form group_nnnn.

All repositories in this course will have a URL of the form: httsp://markus.cdf.toronto.edu/svn/csc207-2016-05/repo-name

s1 drives and s2 navigates.

Now **s1** logs in and opens a new terminal window.

- 1. Change to s1's home directory.
- 2. Check out your group's repository.
- 3. In your repository, you will find a newly created directory called Lab5.
- 4. Open up Eclipse. Point your workspace to the folder repo-name.
- 5. Using Eclipse, create a new Java project called Lab5. Make sure you open the Java perpective.
- 6. Create a new package called lab5.

3 Class Organism take two.

Please study the UML diagram and implement both classes shown there.

Organism is an abstract class. For testing purposes we will instantiate a subclasses of organism called Arthropod.

Again, an Organism has a name, a pair of coordinates (x,y) in the world, and a movement direction chosen among north, south, east, west stored in a static variable VALID_DIRECTIONS. This time we will assume the world is unbounded in all directions. So the move method can easily move the organism in the chosen direction with the desired speed without worrying!

Write the toString and have Eclipse generate getters and setters.

4 The class Arthropod.

Switch roles!

Write the Arthropod class as shown in the UML diagram. Each Arthropod has a different number of legs. Try it! That is, create a test class, instantiate an Arthropod:

Organism lobster = new Arthropod("Homarus gammarus", 0, 0, 2, "north", 10); System.out.println(lobster); lobster.ove(); System.out.println(lobster);

Organism
+VALID_DIRECTIONS: String[] = {"north", "south", "east", "west"}
name: String
xCoord: int
yCoord: int
speed: int
direction: String
+ Organism(String name, xCoord: int, yCoord: int,
direction: String, speed: int)
+ move(): void
+ toString(): String
+ getName(): String
+ setName(String name): void
+ getXCoord(): int
+ setXCoord(int xCoord): void
+ getYCoord(): int
+ setYCoord(int yCoord): void
+ getSpeed(): int
+ setSpeed(int xCoord): void
+ getDirection(): String
+ setDirection(direction: String): void
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Arthropod
- numLegs: int
- rand: java.util.Random
+ Arthropod(String name, xCoord: int, yCoord: int,
speed: int, direction: String, numLegs: int)
+ move(): void
+ toString(): String
+ getNumLegs(): int
+ setNumLegs(int numLegs): void

5 Finishing up

- Show your work to your TA. Make sure to show them the Javadoc.
- Submit your work on Markus.
- If you need help about Assignment 1, don't hesitate to ask!